

Spanning sets and linear independence

Span (continued)

Summary

Given $\vec{v}_1, \dots, \vec{v}_k, \vec{b} \in \mathbb{R}^n$,

$\vec{b} \in \text{span}(\vec{v}_1, \dots, \vec{v}_k) \iff \vec{b}$ is a linear comb. of $\vec{v}_1, \dots, \vec{v}_k \iff [A \mid \vec{b}]$ has a solution, where A is matrix w/columns as $\vec{v}_1, \dots, \vec{v}_k$

Given $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$,

$S = \{\vec{v}_1, \dots, \vec{v}_k\}$ is a spanning set of $\mathbb{R}^n \iff \text{span}(S) = \mathbb{R}^n \iff [A \mid \vec{b}]$ has a solution for any $\vec{b} \in \mathbb{R}^n$

Linear independence

Example Recall we previously found that

$$\begin{bmatrix} -3 \\ 8 \\ -5 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix} - 2 \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}.$$

Rearranging terms, we have

$$3 \underbrace{\begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}}_{\vec{v}_1} - 2 \underbrace{\begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}}_{\vec{v}_2} - \underbrace{\begin{bmatrix} -3 \\ 8 \\ -5 \end{bmatrix}}_{\vec{v}_3} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

Thus, we have a **nontrivial** way to express $\vec{0}$ as a linear combination of $\vec{v}_1, \vec{v}_2, \vec{v}_3$. This is the definition of *linear dependence*.

Definition We say vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ are *linearly dependent* if \exists scalars c_1, c_2, \dots, c_k , not all zero, such that

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_k\vec{v}_k = \vec{0}. \quad (\star)$$

Otherwise, the vectors are *linearly independent*, which means the only solution to (\star) is the trivial solution $c_1 = \dots = c_k = 0$.

To determine if $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ are linearly independent or not, we need to know if \exists nontrivial solution to

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_k\vec{v}_k = \vec{0} \quad \Longrightarrow \quad \underbrace{\left[\begin{array}{ccc|c} | & | & & 0 \\ \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_k & \vdots \\ | & | & & | & 0 \end{array} \right]}_{\text{augmented matrix}}$$

This is a homogeneous linear system! We need to determine if the system has one solution or more than one solution.

$$\vec{v}_1, \dots, \vec{v}_k \text{ are linearly independent} \iff [A \mid \vec{0}] \text{ has a unique solution, namely } \vec{0} \text{ (where } A \text{ has } \vec{v}_1, \dots, \vec{v}_k \text{ as columns)}$$

Example Are the following vectors linearly independent?

$$\begin{bmatrix} 0 \\ 1 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 8 \end{bmatrix}, \begin{bmatrix} 4 \\ -1 \\ 0 \end{bmatrix}$$

We do EROs on the appropriate augmented matrix to get

$$\left[\begin{array}{ccc|c} 0 & 1 & 4 & 0 \\ 1 & 2 & -1 & 0 \\ 5 & 8 & 0 & 0 \end{array} \right] \xrightarrow{\text{EROs}} \left[\begin{array}{ccc|c} 1 & 2 & -1 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & 13 & 0 \end{array} \right].$$

We see that there are no free variables (i.e., every column has a leading entry), so the system has a unique solution, $\vec{0}$. Thus, the vectors are

linearly independent.

Theorem.

Vectors $\vec{v}_1, \dots, \vec{v}_k$ are linearly dependent

if and only if

one of the vectors can be written as a linear combination of the others.

Facts Let $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ be a set of vectors in \mathbb{R}^n .

- (1) If $\vec{v}_i = \vec{0}$ for some i , then S is linearly dependent.
- (2) If one vector in S is a linear combination of the other vectors in S , then S is linearly dependent.
- (3) If $k > n$ (more vectors than components), then S is linearly dependent.

Homogeneous system w/more variables than equations must have a free variable.

Example Is $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -10 \\ 21 \\ -5 \end{bmatrix}, \begin{bmatrix} 0 \\ -\frac{1}{7} \\ 7 \end{bmatrix} \right\}$ linearly independent?

No! The vectors are linearly dependent since we have 4 vectors in \mathbb{R}^3 . (See fact 3 above.)

Matrices

At its core, linear algebra is the study of linear transformations and their algebraic properties. We'll see, down the road, that there is an intimate relationship between a linear transformation and a matrix.

Recall...

Definition A *matrix* is a rectangular array of numbers.

Example $A = \begin{bmatrix} 1 & 2 \\ -\frac{3}{2} & 3 \\ 0 & -5 \end{bmatrix}$ is a 3×2 matrix.

a_{ij} denotes the entry of A in row i and column j , so, for example, $a_{12} = 2$ and $a_{21} = -\frac{3}{2}$.

Definition If A is an $n \times n$ matrix (i.e., # of rows = # of cols.), then we say that A is a *square matrix*.

Matrix operations

- **Equality:**

$$A = B \iff A, B \text{ are same size and } a_{ij} = b_{ij} \forall i, j$$

- **Matrix addition:** A, B are $m \times n$ matrices

$$C = A + B \text{ is the } m \times n \text{ matrix defined as } c_{ij} = a_{ij} + b_{ij} \forall i, j$$

add entrywise

- **Scalar multiplication:** $m \times n$ matrix A , scalar c

$$cA \text{ is the } m \times n \text{ matrix with entries } ca_{ij} \forall i, j$$

Example

$$2 \begin{bmatrix} 2 & \frac{5}{2} & 1 \\ -1 & 0 & 2 \end{bmatrix} + \begin{bmatrix} 3 & 1 & -4 \\ 1 & 5 & 2 \end{bmatrix} = \begin{bmatrix} 7 & 6 & -2 \\ -1 & 5 & 6 \end{bmatrix}$$

Remark The set of all $m \times n$ matrices with real entries (denoted $\mathbb{R}^{m \times n}$ or $M_{m \times n}(\mathbb{R})$) with the operations of matrix addition and scalar multiplication form a vector space.

A, B, C are $m \times n$ matrices, c, d are scalars

- (1) $A + B$ is an $m \times n$ matrix (closure under addition)
- (2) $A + B = B + A$ (commutativity)
- (3) $(A + B) + C = A + (B + C)$ (associativity)
- (4) $A + 0 = A$ (existence of additive identity)
- (5) $A + (-A) = 0$ (existence of additive inverses)
- (6) cA is an $m \times n$ matrix (closure under scalar multiplication)
- (7) $c(A + B) = cA + cB$ (distributivity)
- (8) $(c + d)A = cA + dA$ (distributivity)
- (9) $c(dA) = (cd)A$
- (10) $1A = A$

Matrix multiplication \implies see slides

Matrix multiplication

Math 40, Introduction to Linear Algebra

Monday, January 30, 2012



Matrix-vector multiplication: two views

- 1st perspective: $A\vec{x}$ is linear combination of columns of A

$$\begin{matrix} \begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \\ A \end{matrix} \begin{matrix} \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} \\ \vec{x} \end{matrix} = 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Matrix-vector multiplication: two views

- 1st perspective: $A\vec{x}$ is linear combination of columns of A

$$\begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} = 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} -2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \boxed{\begin{bmatrix} 4 \\ 21 \end{bmatrix}}$$

A \vec{x}

- 2nd perspective: $A\vec{x}$ is computed as dot product of rows of A with vector \vec{x}

$$\begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} = \left[\begin{array}{l} \text{dot product of } \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} \text{ and } \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} \\ \text{dot product of } \begin{bmatrix} 2 \\ 1 \\ 5 \end{bmatrix} \text{ and } \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} \end{array} \right]$$

A \vec{x}

Matrix-vector multiplication: two views

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A \vec{x}

Notice that **# of columns of A = # of rows of \vec{x}** .

This is a requirement in order for matrix multiplication to be defined.

Matrix multiplication (in general)

$$\begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 4 & 2 & 1 \\ 3 & 0 & 2 \\ 2 & 1 & 3 \end{bmatrix}$$

A B

Note that
cols. of A = # of rows of B

$$AB = \begin{bmatrix} & A & \end{bmatrix} \begin{bmatrix} \left| \begin{array}{c} \vec{b}_1 \\ \vec{b}_2 \\ \dots \\ \vec{b}_p \end{array} \right. \end{bmatrix} = \begin{bmatrix} \left| \begin{array}{c} A\vec{b}_1 \\ A\vec{b}_2 \\ \dots \\ A\vec{b}_p \end{array} \right. \end{bmatrix}$$

$m \times n$ $n \times p$ $m \times p$

Each column of AB is a linear combination of columns of A .

Matrix multiplication (in general)

$$\begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 4 & 2 & 1 \\ 3 & 0 & 2 \\ 2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 5 & 6 \\ 21 & 9 & 19 \end{bmatrix}$$

A B

Note that
cols. of A = # of rows of B

Computing AB via linear combinations of columns of A :

$$\text{1st column of } AB = 4 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} -2 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 4 \\ 21 \end{bmatrix}$$

$$\text{2nd column of } AB = 2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 0 \begin{bmatrix} -2 \\ 1 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 5 \\ 9 \end{bmatrix}$$

$$\text{3rd column of } AB = 1 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 2 \begin{bmatrix} -2 \\ 1 \end{bmatrix} + 3 \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} 6 \\ 19 \end{bmatrix}$$

While you should understand this approach, it is often easier to multiply matrices via dot products.

Matrix multiplication (in general)

In terms of dot products,

$$\text{the } (i,j)\text{-entry of } AB = [\textit{ith row of } A] \cdot [\textit{jth column of } B]$$

viewed as column vectors

$$\begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 4 & 2 & 1 \\ 3 & 0 & 2 \\ 2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & & \\ & & \\ & & \end{bmatrix}$$

A B

since $\begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 4 \\ 3 \\ 2 \end{bmatrix} = 4$

Matrix multiplication (in general)

In terms of dot products,

$$\text{the } (i,j)\text{-entry of } AB = [\textit{ith row of } A] \cdot [\textit{jth column of } B]$$

viewed as column vectors

$$\begin{bmatrix} 1 & -2 & 3 \\ 2 & 1 & 5 \end{bmatrix} \begin{bmatrix} 4 & 2 & 1 \\ 3 & 0 & 2 \\ 2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 5 & 6 \\ 21 & 9 & 19 \end{bmatrix}$$

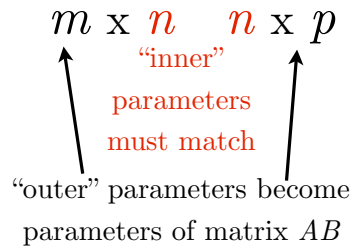
A B

since $\begin{bmatrix} 2 \\ 1 \\ 5 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = 19$

Matrix multiplication

What sizes of matrices can be multiplied together?

For $m \times n$ matrix A and $n \times p$ matrix B , the matrix product AB is an $m \times p$ matrix.



If A is a square matrix and k is a positive integer, we define

$$A^k = \underbrace{A \cdot A \cdots A}_{k \text{ factors}}$$