LECTURE 7: THE DERIVATIVE OF $F:\mathbb{R}^N\to\mathbb{R}$

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1. LIMITS

In our last lecture, we discussed the tangent plane to the graph of a function f(x, y). The differentiability of f is related to this tangent plane, and a rigorous definition of differentiability requires the notion of limit.

Definition 1. Let $f : \mathbb{R}^n \to \mathbb{R}^m$ be a multivariable function, and $\mathbf{x} = (x_1, \dots, x_n)$ be coordinates of \mathbb{R}^n and $\mathbf{a} \in \mathbb{R}^n$ be a point. Then the limit of f as \mathbf{x} approaches \mathbf{a} is equal to L *if*, for every $\varepsilon > 0$ there exists $\delta > 0$ such that

 $|\mathbf{x} - \mathbf{a}| < \delta$

implies

$$|f(\mathbf{x}) - f(\mathbf{a})| < \varepsilon$$

In that case, we write

 $\lim_{\mathbf{x}\to\mathbf{a}}\mathsf{f}(\mathbf{x})=\mathsf{L}.$



FIGURE 1. The idea of limit.

This definition is directly analogous to the definition of limit for a function of a single variable. Of course, in this higher dimensional version, there are (infinitely) more than two directions to check (as opposed to only left and right hand limits) for a limit to exits.

Also, we have a definition of continuity which directly generalizes the single variable case.

Definition 2. *The function* $f : \mathbb{R}^n \to \mathbb{R}^m$ *is* continuous at a *if*

$$\lim_{\mathbf{x}\to\mathbf{a}}\mathsf{f}(\mathbf{x})=\mathsf{f}(\mathbf{a}).$$

If $U \subset \mathbb{R}^n$ *is a subset and* f *is continuous at* **a** *for all* **a** \in U, *then* f *is* continuous on U.

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2. DERIVATIVE

Using our notion of limit, we can define differentiability of our functions of two variables.

Definition 3. The function $f : \mathbb{R}^2 \to \mathbb{R}$ is differentiable at (a, b) if f_x and f_y exist and, for

$$h(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b),$$

we have

$$\lim_{(\mathbf{x},\mathbf{y})\to(\mathbf{a},\mathbf{b})}\frac{\mathbf{f}(\mathbf{x},\mathbf{y})-\mathbf{h}(\mathbf{x},\mathbf{y})}{|(\mathbf{x},\mathbf{y})-(\mathbf{a},\mathbf{b})|}=\mathbf{0}.$$

Remark 4. We say that h(x, y) is a good linear approximation of f(x, y) at (a, b) in case f is differentiable at (a, b), and the plane z = h(x, y) is the tangent plane to f(x, y) at (a, b).

Example 5. Let $f(x, y) = x^2 + y^2$. What is the tangent plane to z = f(x, y) at the point (1,2)? We compute

$$f_x = 2x \qquad \qquad f_y = 2y$$

Thus $f_x(1,2) = 2$ and $f_u(1,2) = 4$. Also f(1,2) = 5. Thus the tangent plane at (1,2) is

$$z = h(1,2) = 5 + 2(x-1) + 4(y-2).$$

Example 6. Let's see that this h is in fact a good approximation for f in the previous example. We approximate f(1.02, 1.95).

$$(1.02)^{2} + (1.95)^{2} \sim 5 + 2(.02) + 4(-.05) = 4.84.$$

The actual value is 4.8429.

Proposition 7. The function f(x, y) is differentiable at (a, b) if f_x and f_y exist and are continuous in a neighborhood of (a, b).

Note that we may rewrite h as follows.

$$\begin{split} h(x,y) &= f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b) \\ &= f(a,b) + \left(\frac{\partial f}{\partial x}(a,b), \frac{\partial f}{\partial y}(a,b)\right) \cdot ((x-a), (y-b)). \end{split}$$

It is useful to introduce notation for this vector $\left(\frac{\partial f}{\partial x}(a,b), \frac{\partial f}{\partial y}(a,b)\right)$. It is called the *gradient of* f and denoted ∇f . In fact, we can define such an object for functions $\mathbb{R}^n \to \mathbb{R}$.

Definition 8. Let $f : \mathbb{R}^n \to \mathbb{R}$ be a function. The gradient of f is the vector of partial derivatives

$$\nabla f = \left(\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n}\right).$$

Using this notation, we have the following expression for our tangent plane to the graph of f(x, y) at the point (a, b, f(a, b)),

$$h(\mathbf{x},\mathbf{y}) = f(\mathbf{a},\mathbf{b}) + \nabla f(\mathbf{a},\mathbf{b}) \cdot (\mathbf{x} - \mathbf{a},\mathbf{y} - \mathbf{b}).$$

We can now generalize our notion of differentiability to functions on \mathbb{R}^n .

Definition 9. The function $f : \mathbb{R}^n \to \mathbb{R}$ is differentiable at the point $\mathbf{a} = (a_1, \dots, a_n) \in \mathbb{R}^n$ if all partial derivatives $\frac{\partial f}{\partial x_i}$ exist, for $i = 1, \dots, n$ and, for

$$h(\mathbf{x}) = f(\mathbf{a}) + \nabla f(\mathbf{a}) \cdot (\mathbf{x} - \mathbf{a}),$$

this limit vanishes,

$$\lim_{\mathbf{x}\to\mathbf{a}}\frac{f(\mathbf{x})-h(\mathbf{x})}{|(\mathbf{x})-(\mathbf{a})|}=\mathbf{0}.$$

Remark 10. Again, this indicates that the function h is the best linear approximation of f near the point **a**.